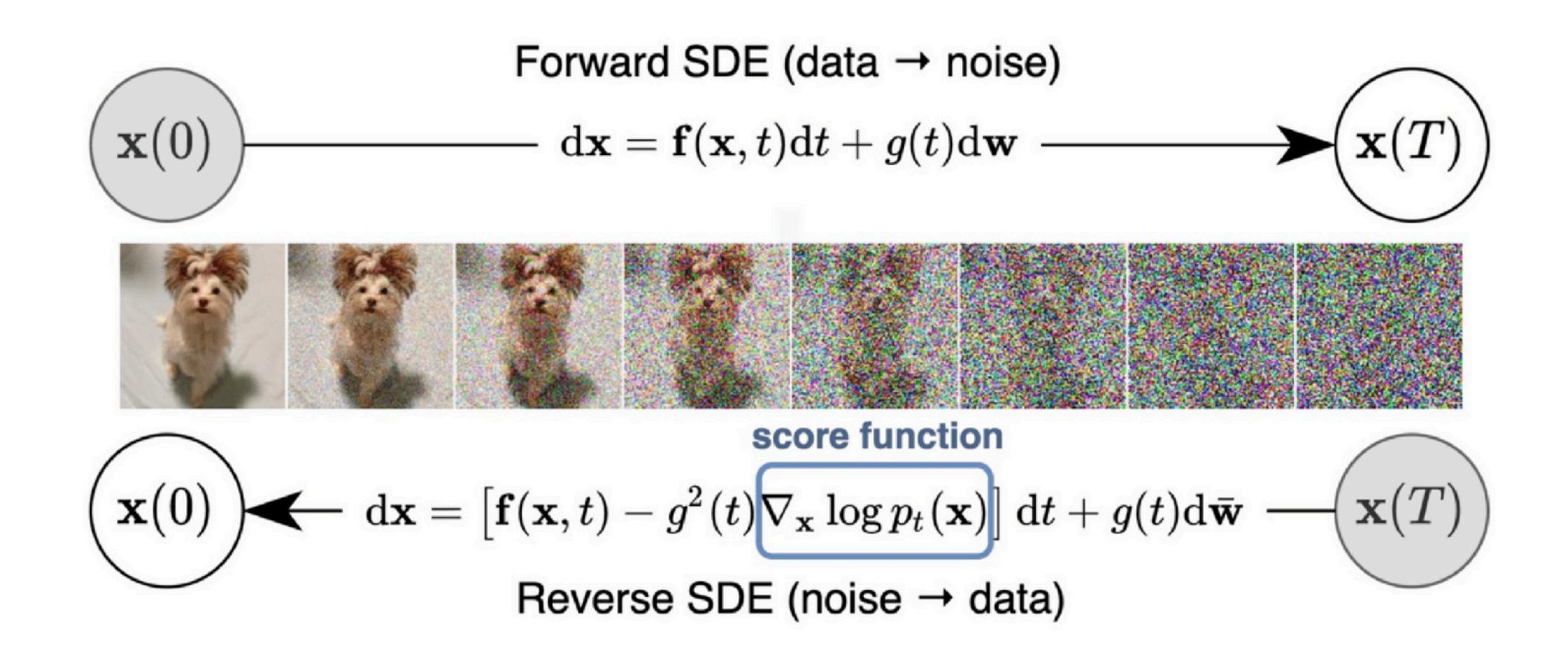
Initial noise in generative models

Background

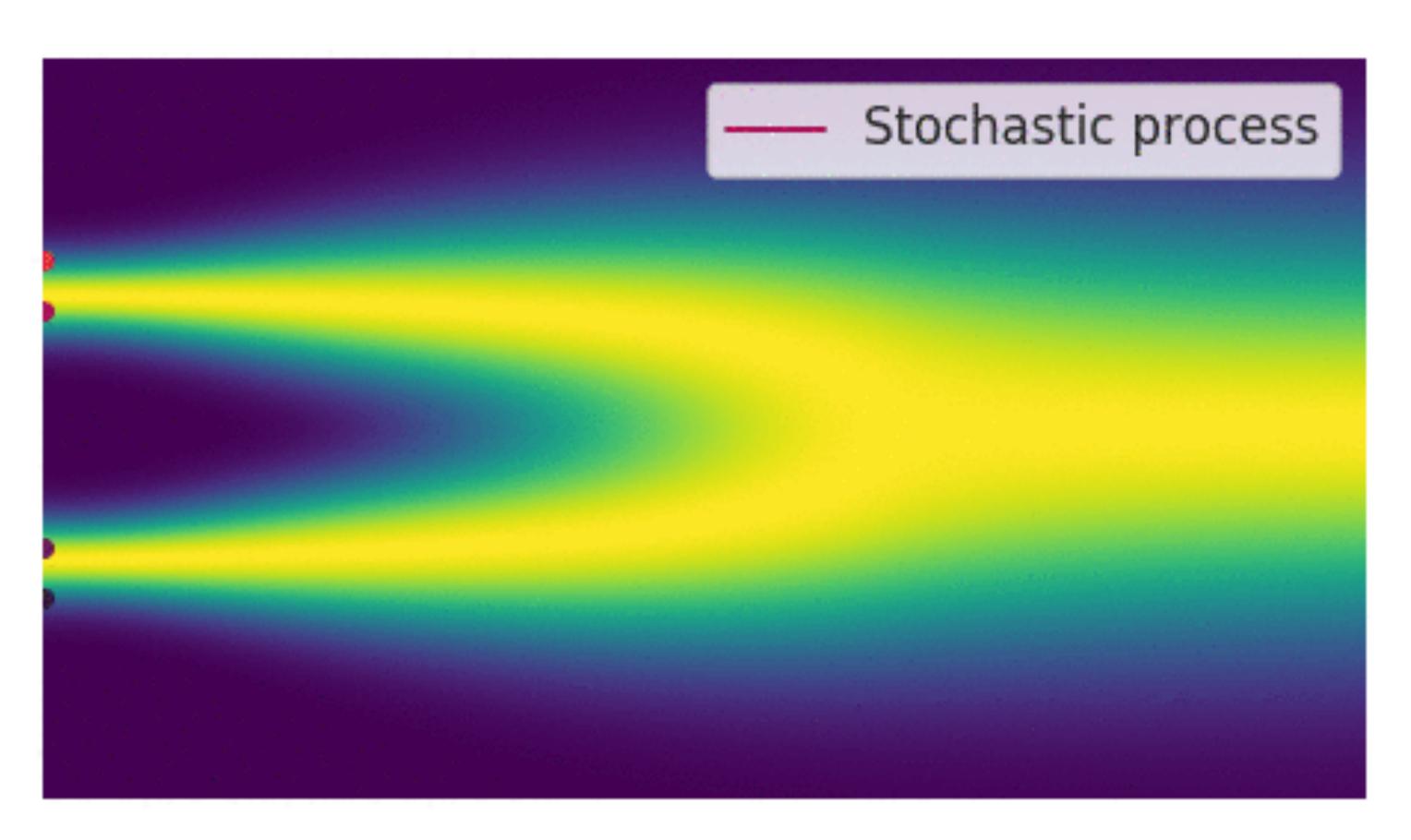
Diffusion Models



Background

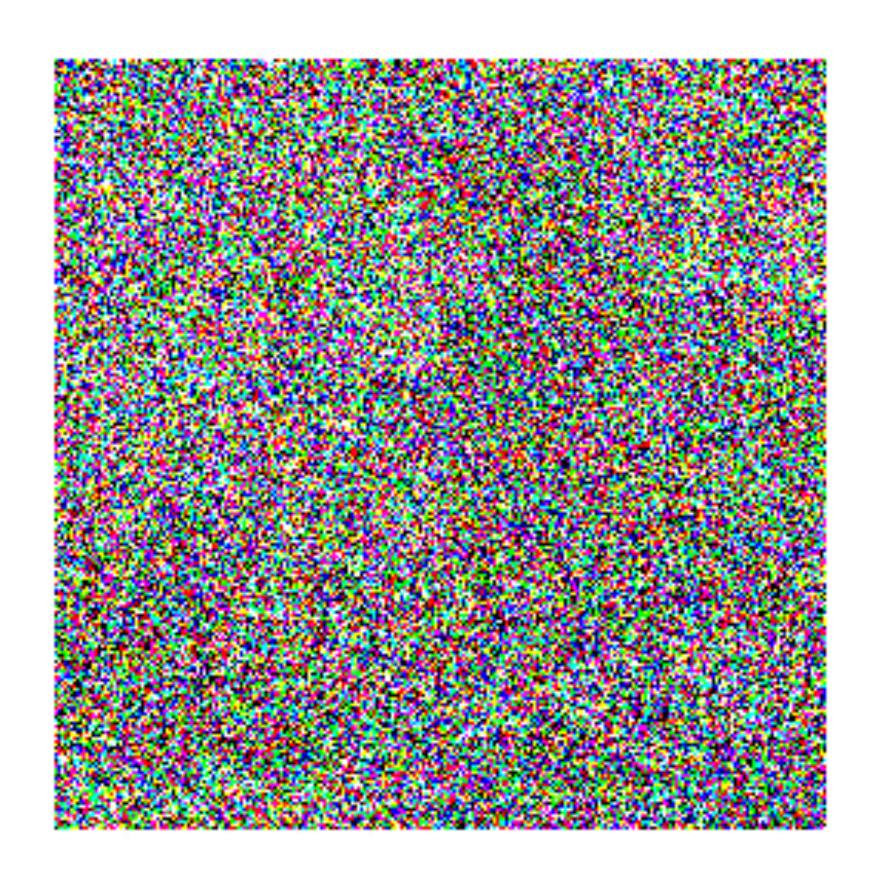
Forward Process

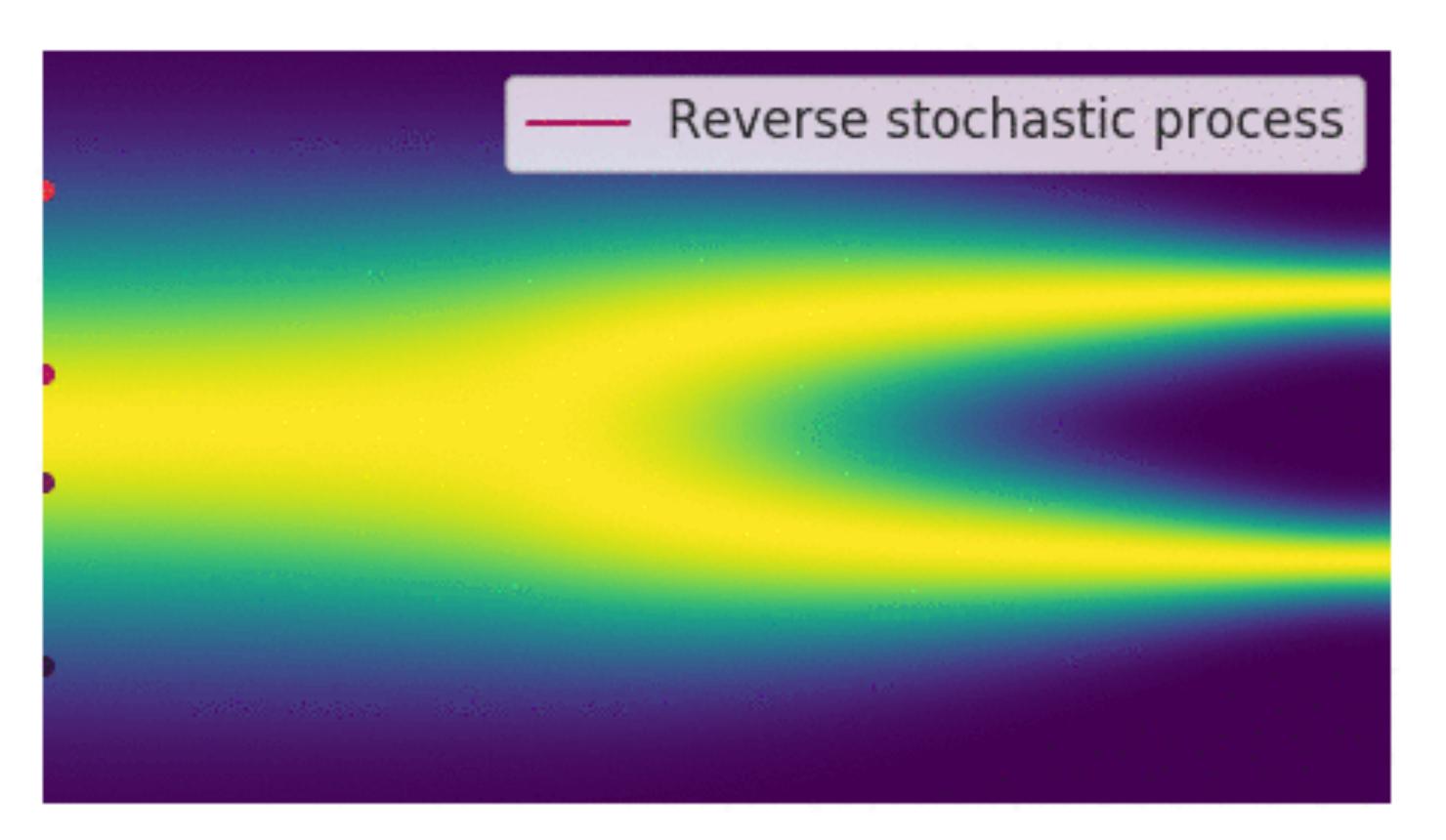




Background

Reverse Process





Observation

Seed 2913422709 Seed 2489154832 Seed 3600226442 A fluffy baby sloth with Prompt a knitted hat trying to **Initial** figure out a laptop. NULL Noise Mismatch Match

SD 1.5

SDXL

NoiseQuery as Implicit Guidance for Goal-Driven Image Generation

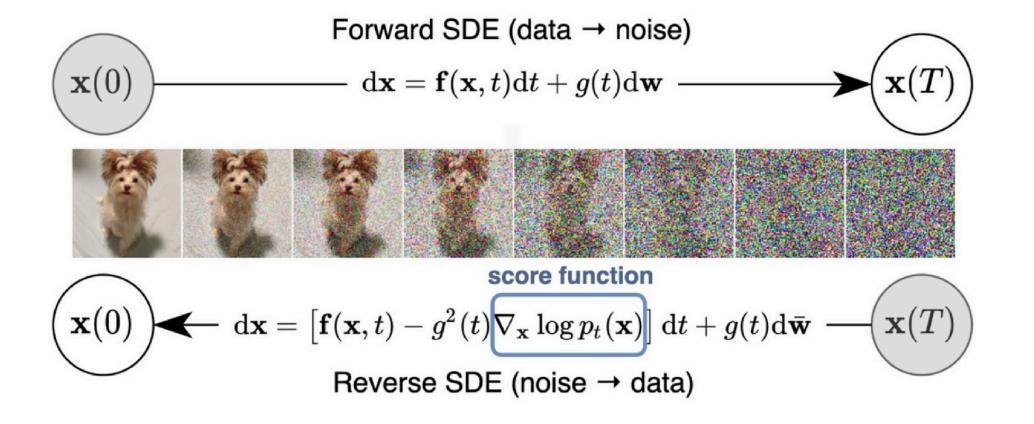
Cross-model similarities when generating with same initial noise

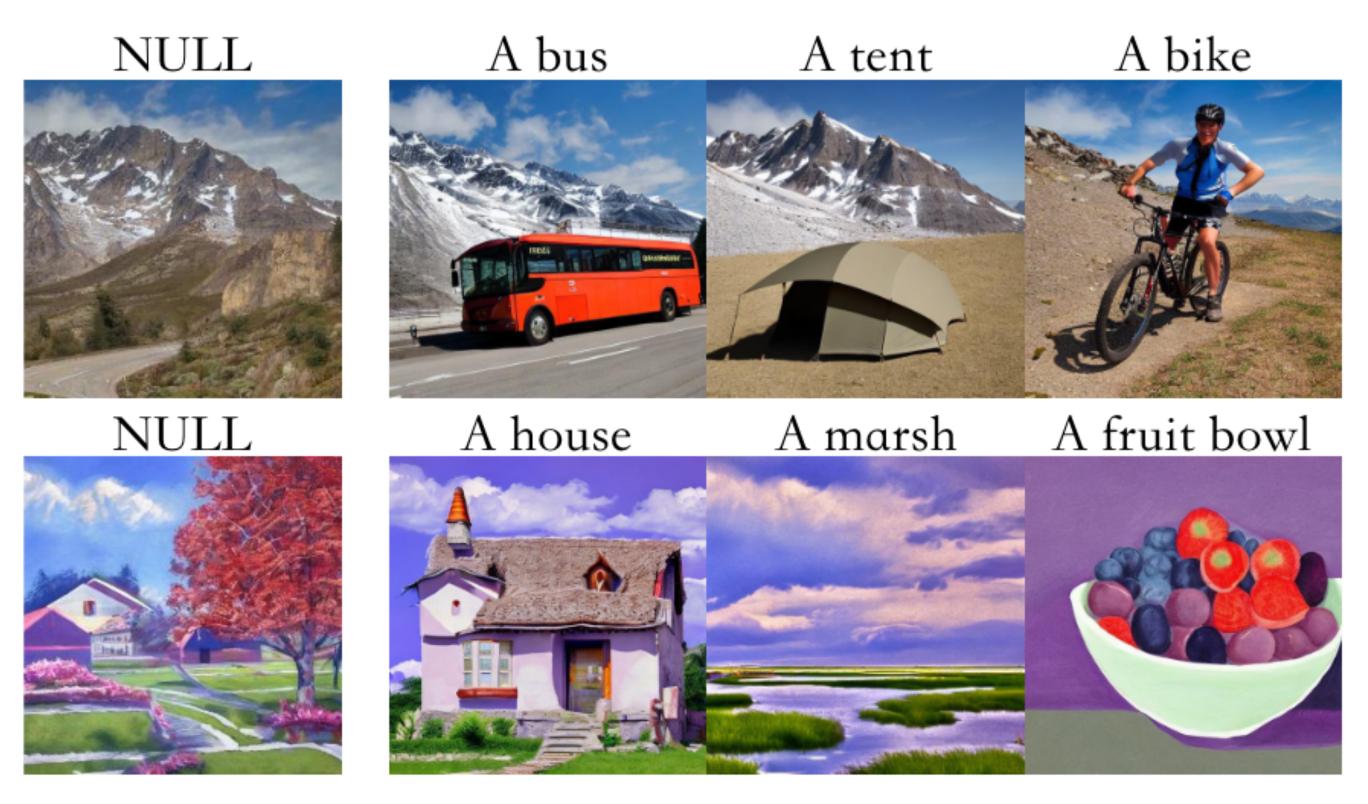


NoiseQuery as Implicit Guidance for Goal-Driven Image Generation

- Similar colors, texture, sharpness
- Implicitly encodes clues

$$x_T = 0.068265 \cdot x_0 + 0.997667 \cdot \epsilon$$

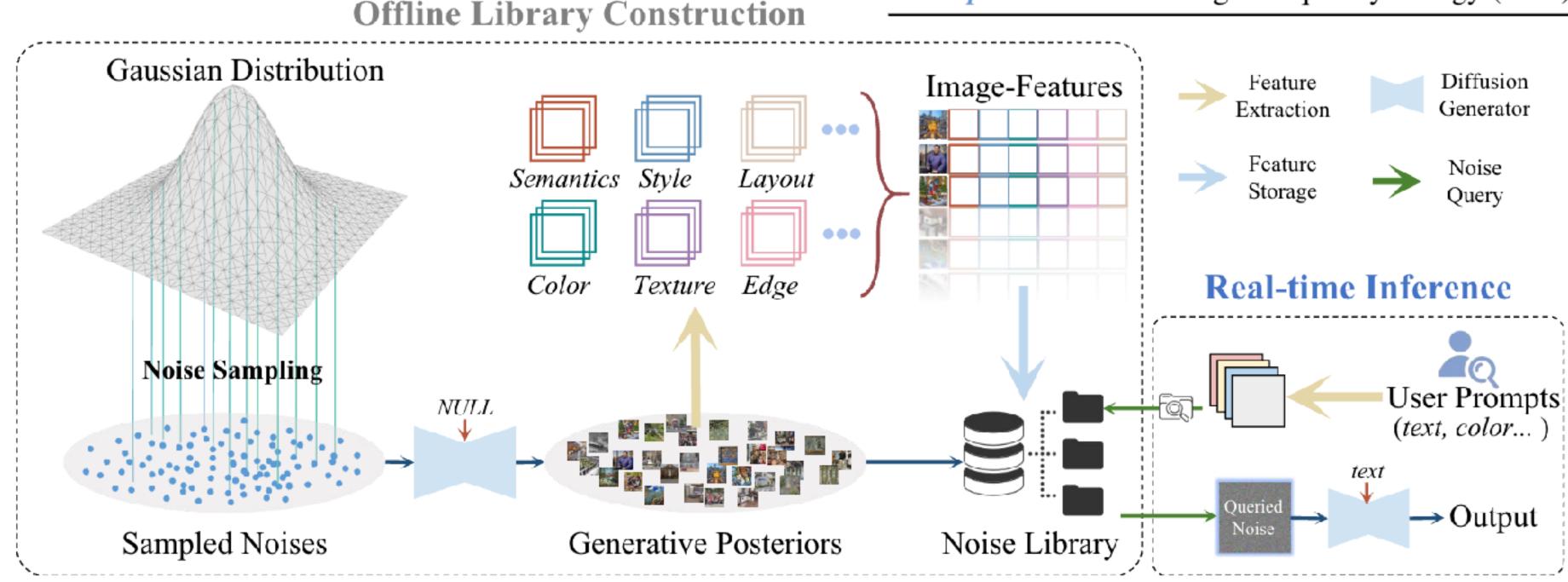




NoiseQuery as Implicit Guidance for Goal-Driven Image Generation

• 100k random noise samples

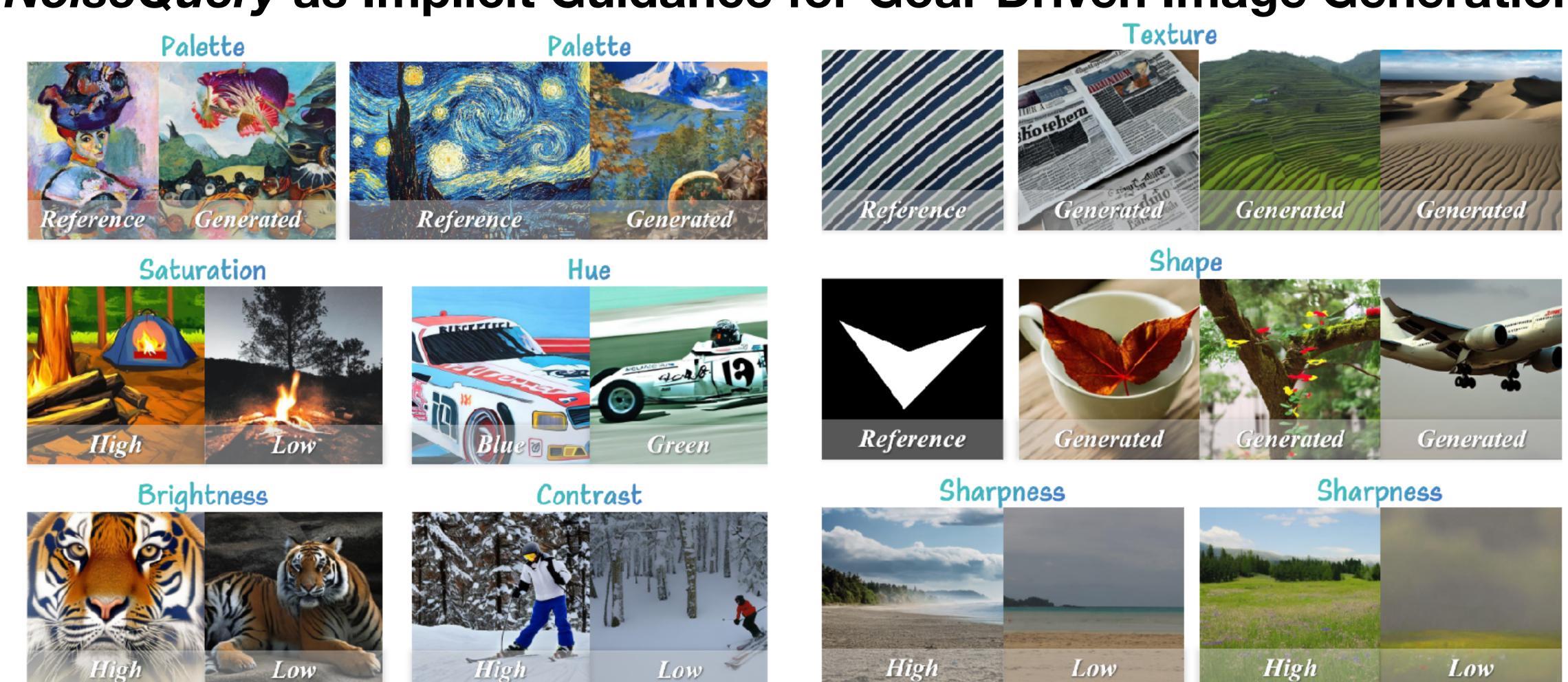
Generation Goals	Feature Type	Match Function
Semantics	CLIP [42], BLIP [29]	Cosine Similarity
Style	Gram Matrix [16]	MSE
Color	RGB, HSV, LAB	Absolute Difference
Texture	GLCM [19]	Euclidean Distance
Shape	Hu Moments [22]	Euclidean Distance
Sharpness	High Frequency Energy (HFE)	Absolute Difference



NoiseQuery as Implicit Guidance for Goal-Driven Image Generation

Base Model	Method	DrawBench [47]			MSCOCO [33]				Time Cost	
Dusc Wiodei		ImageReward	PickScore	HPS v2	CLIPScore	ImageReward	PickScore	HPS v2	CLIPScore	Time Cost
SD 1.5	Base Model	0.04	21.11	24.57	30.90	0.15	21.41	25.65	31.08	1.334 s
	+ NoiseQuery	0.08	21.16	25.02	31.41	0.27	21.48	26.07	31.47	1.336 s
	+ Diffusion-DPO [53]	0.09	21.29	25.02	31.19	0.25	21.64	26.31	31.26	1.350 s
	+ Diffusion-DPO [53] + NoiseQuery	0.17	21.33	25.25	31.41	0.35	21.68	26.60	31.55	1.352 s
SD 2.1	Base Model	0.12	21.33	24.93	31.13	0.36	21.72	26.58	31.40	1.301 s
	+ NoiseQuery	0.26	21.46	25.39	31.68	0.44	21.76	26.82	31.50	1.303 s
	+ CFG++ [10]	0.12	21.33	24.83	31.13	0.37	21.72	26.66	31.31	3.724 s
	+ CFG++ [10] + NoiseQuery	0.27	21.43	25.55	31.61	0.47	21.76	26.97	31.67	3.726 s
SD-Turbo	Base Model	0.26	21.78	25.23	31.29	0.47	22.07	26.22	31.51	0.072 s
	+ NoiseQuery	0.41	21.87	25.66	31.58	0.50	22.17	26.82	31.76	0.074 s
	+ ReNO [11]	1.67	23.40	32.48	32.55	-				23.56 s
	+ ReNO [11] + NoiseQuery	1.71	23.52	32.92	32.78	-	-	-	-	23.56 s
PixArt- α	Base Model	0.70	22.08	28.27	30.83	0.78	22.24	29.33	31.48	4.327 s
	+ NoiseQuery	0.82	22.11	28.45	31.27	0.79	22.33	29.56	31.64	4.328 s
	+ LaVi-Bridge [67]	0.63	22.08	28.35	30.92	0.75	22.31	29.49	31.86	5.092 s
	+ LaVi-Bridge [67] + NoiseQuery	0.72	22.24	28.61	31.35	0.78	22.35	29.67	32.01	5.094 s

NoiseQuery as Implicit Guidance for Goal-Driven Image Generation



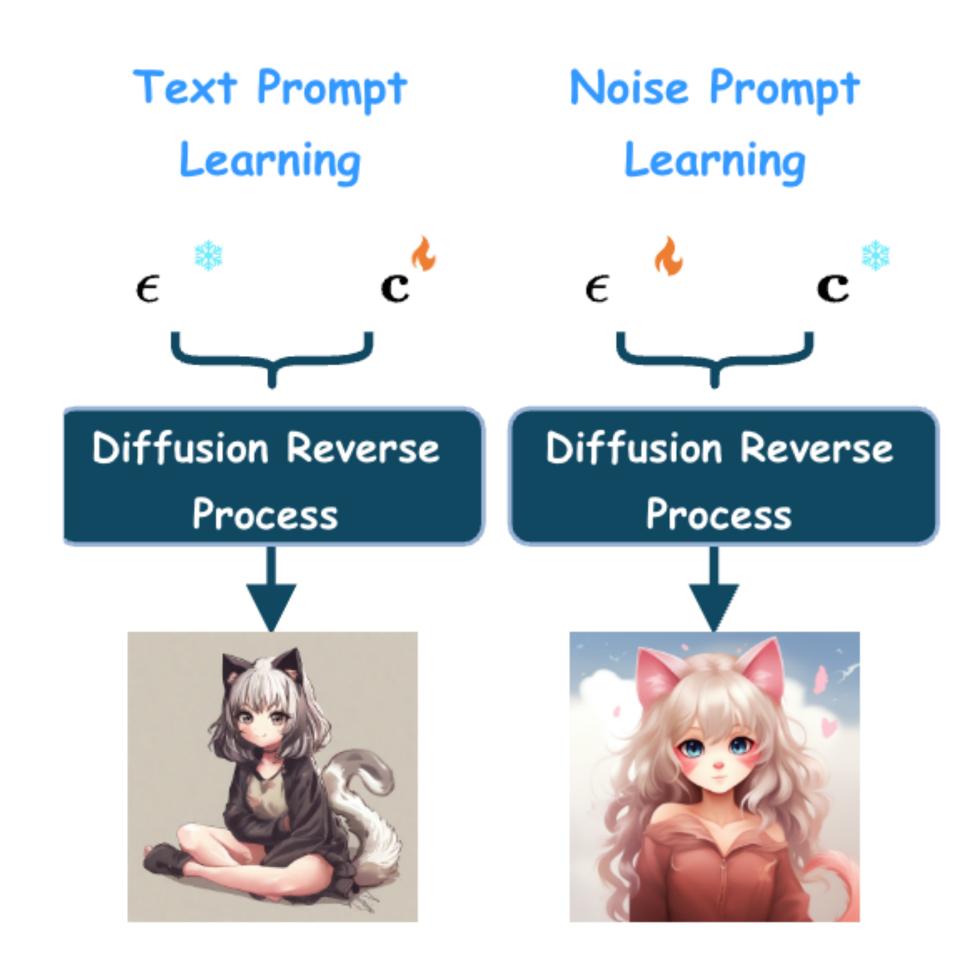
(a) Color properties guidance.

(b) Structural features guidance.

A Learning Framework

Text Prompt Learning & Noise Prompt Learning

$$\phi^* = \arg\min_{\phi} \mathbb{E}_{(\mathbf{x}_{T_i}, \mathbf{x}'_{T_i}, \mathbf{c}_i) \sim \mathcal{D}} [\ell(\phi(\mathbf{x}_{T_i}, \mathbf{c}_i), \mathbf{x}'_{T_i})].$$



A Learning Framework

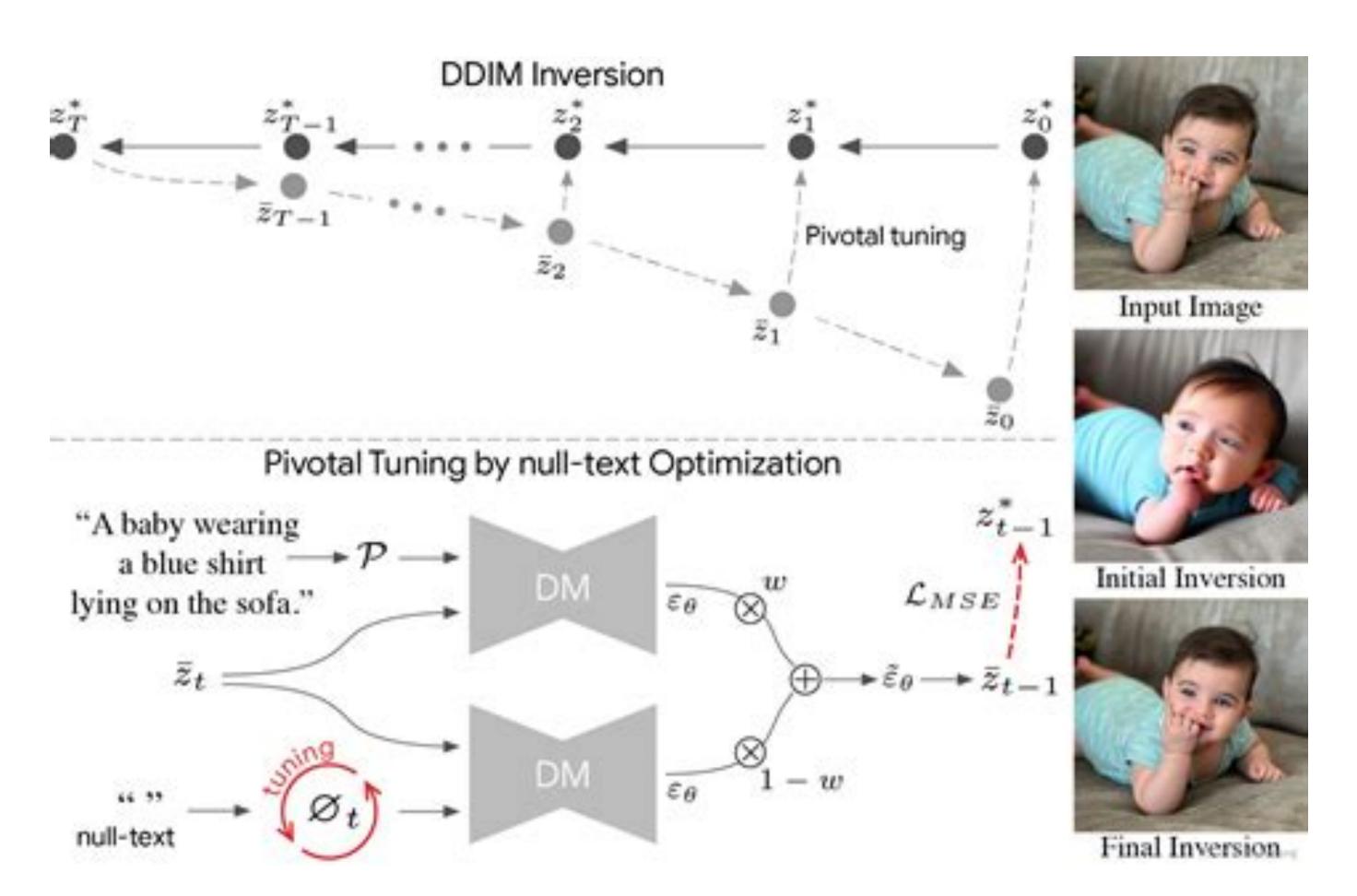
DDIM Inversion

$$\mathbf{x}_{t-1} = \text{DDIM}(\mathbf{x}_t)$$

$$= \alpha_{t-1} \left(\frac{\mathbf{x}_t - \sigma_t \epsilon_{\theta}(\mathbf{x}_t, t)}{\alpha_t} \right) + \sigma_{t-1} \epsilon_{\theta}(\mathbf{x}_t, t)$$
(1)

$$\mathbf{x}_{t} = \text{DDIM-Inversion}(\mathbf{x}_{t-1})$$

$$= \frac{\alpha_{t}}{\alpha_{t-1}} \mathbf{x}_{t-1} + \left(\sigma_{t} - \frac{\alpha_{t}}{\alpha_{t-1}} \sigma_{t-1}\right) \epsilon_{\theta}(\mathbf{x}_{t}, t)$$
(2)



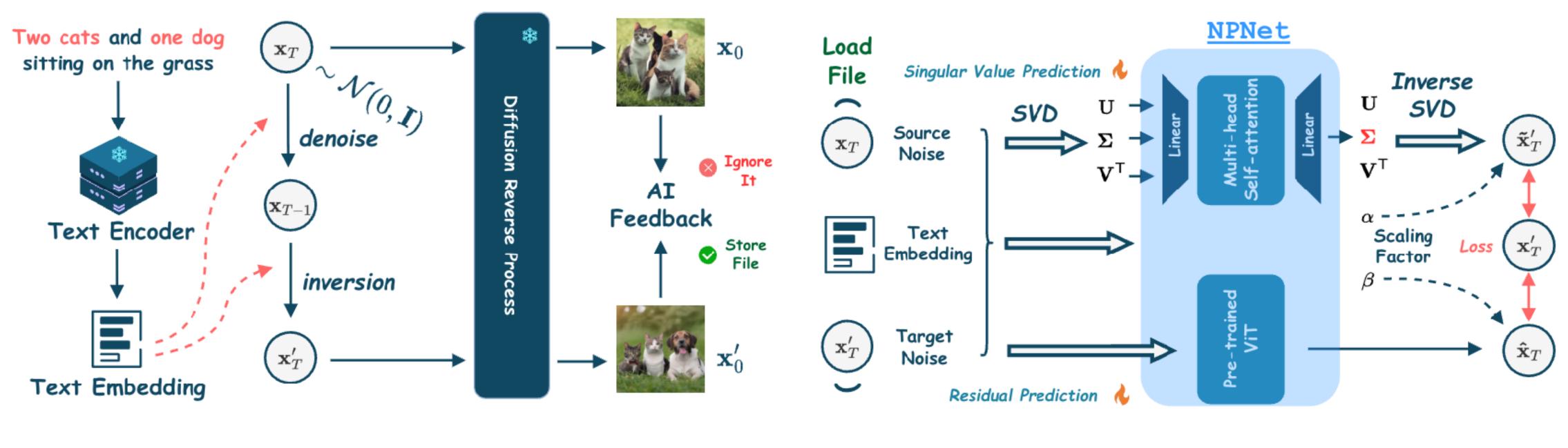
A Learning Framework

$$\mathbf{e} = \sigma(\mathbf{x}_T, \mathcal{E}(\mathbf{c})) \quad \hat{\mathbf{x}}_T = \varphi'(\psi(\varphi(\mathbf{x}_T + \mathbf{e})).$$

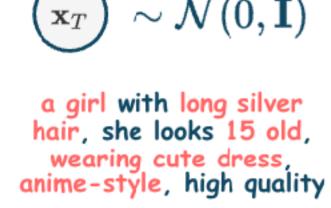
 $\mathcal{L}_{ ext{MSE}} = ext{MSE}(\mathbf{x}_T', \mathbf{x}_{T_{pred}}'),$ where $\mathbf{x}_{T_{pred}}' = \tilde{\mathbf{x}}_T' + \beta \hat{\mathbf{x}}_T,$

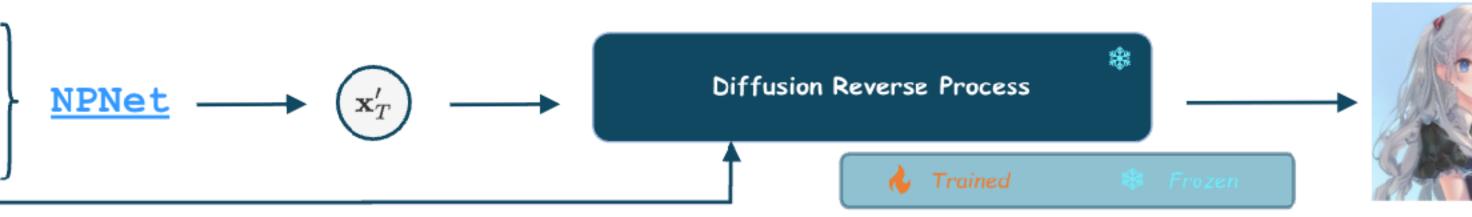












A Learning Framework

Standard

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A photo of a traffic light and a backpack.

A photo of a donut.

A photo of a stop sign.

A photo of a horse and a train.

A photo of three oranges.

A Learning Framework



A photo of three benchs.

A photo of a car.

A photo of a stop sign and a dog.

A photo of a person and a bear.

A photo of a bus.

A Learning Framework

Model	Dataset	Method	PickScore (↑)	HPSv2 (↑)	AES (↑)	ImageReward (↑)	CLIPScore (↑)	$MPS(\%) (\uparrow)$
SDXL	Pick-a-Pic	Standard	21.69	28.48	6.0373	58.01	0.8204	-
		Inversion 1	21.71	28.57	6.0503	63.27	0.8250	51.41
		NPNet (ours)	21.86	28.68	6.0540	65.01	0.8408	52.14
	DrawBench	Standard	22.31	26.72	5.5952	62.21	0.8077	-
		Inversion	22.37	26.91	5.6017	67.09	0.8081	51.98
		NPNet (ours)	22.38	27.14	5.6034	70.67	0.8153	53.70
	HPD	Standard	22.88	29.71	5.9985	96.63	0.8734	-
		Inversion	22.89	29.78	5.9948	97.39	0.8708	53.03
		NPNet (ours)	22.94	29.88	5.9922	98.81	0.8813	56.02
DreamShaper-xl-v2-turbo	Pick-a-Pic	Standard	22.41	32.12	6.0161	98.09	0.8267	-
		Inversion	22.40	32.03	6.0236	100.97	0.8277	49.14
		NPNet (ours)	22.73	32.69	6.0646	106.74	0.8958	52.34
	DrawBench	Standard	22.98	30.39	5.6735	98.84	0.8186	-
		Inversion	22.94	30.10	5.6852	96.74	0.8189	46.62
		NPNet (ours)	23.11	30.78	5.7005	108.14	0.8224	53.53
	HPD	Standard	23.68	30.96	6.1408	129.89	0.8868	-
		Inversion	23.67	31.00	6.0811	131.80	0.8912	46.94
		NPNet (ours)	23.70	34.08	6.1283	135.98	0.8942	52.49